

Sub E7  
Db wherein respective adhesive strengths A, B and C are set to have a relation of  $A < B < C$ , where A designates adhesive strength between the adhesive surface of said adhesive tape and said support body, B designates adhesive strength between the non-adhesive surface of said adhesive tape and said attaching roller, and C designates adhesive strength between the adhesive surface of said adhesive tape and said member.

2. (Previously Amended) A method for attaching an adhesive tape according to claim 1, wherein said support body comprises a conveyor belt that has been subjected to a reduction treatment to reduce adhesivity between the adhesive surface of said adhesive tape and said support body.

3. (Previously Amended) A method for attaching an adhesive tape according to claim 2, further comprising the step of:  
cutting a roll-form adhesive tape into adhesive tape pieces having a predetermined length,

wherein said adhesive tape pieces are disposed one by one on said conveyor belt with their adhesive surfaces down such that said adhesive surface is in contact with said conveyor belt, and said adhesive tape pieces are conveyed by said conveyor belt to a position where said adhesive tape pieces are transferred onto said attaching roller.

4. – 10. (Cancelled)

11. (Currently Amended) The method of claim 1, further comprising moving and/or rotating the attaching roller along at least one of X, Y, Z, and  $\theta$  axes to position and roll the attaching roller into on a surface of the member located in the predetermined position.

12. (Previously Added) The method of claim 1, wherein said member is a curved glass panel and said attaching roller is rolled onto a slanted upper or a slanted lower surface of said curved glass panel to transfer said adhesive tape to said slanted upper or slanted lower surface of said curved glass panel.

13. (Previously Added) The method of claim 12, wherein said attaching roller is manipulated by a hand portion of a multi-axis robot.

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14. (Currently Amended) The method of claim 1, wherein excessive pressure is prevented from being applied to said member by means of ~~an elastic~~ a flexible support portion of said attaching roller.

Please enter the following new claim:

15. (New) The method of claim 11, wherein the  $\theta$  axis is a yaw axis perpendicular to a rolling axis of the attaching roller.

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